COMPOSITE VIDEO SIGNAL

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Consist of:

- Camera signal corresponding to the desired picture information
- Blanking pulses to make the retrace invisible
- Synchronizing pulses to synchronize the transmitter and receiver scanning
 - -horizontal sync pulse
 - -vertical sync pulse
 - -their amplitudes are kept same
 - -but their duration are different
 - -needed consecutively and not simultaneously with the picture signal so sent on a time division basis

Composite Video Signal

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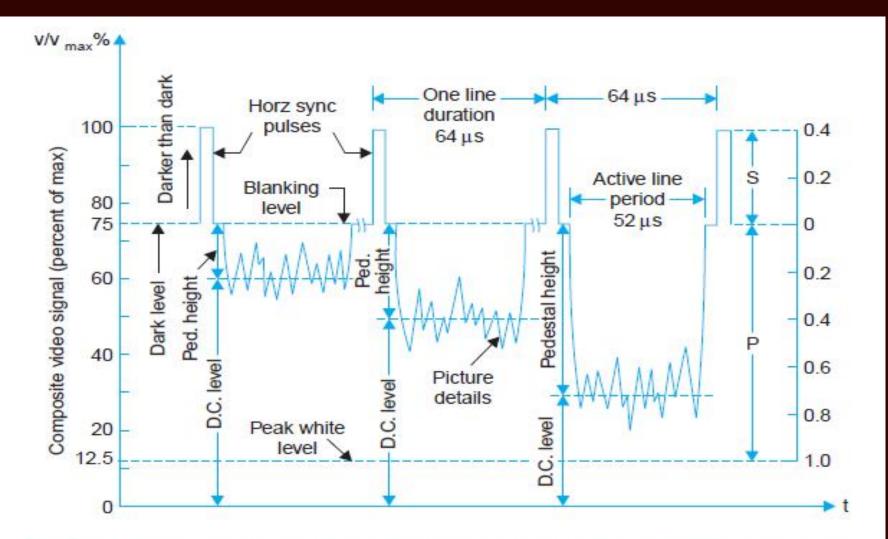


Fig. 3.1 Arbitrary picture signal details of three scanning lines with different average brightness levels. Note that picture to sync ratio P/S = 10/4.

Composite video signal

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Video signal varies between certain limits

Peak white level: 10 to 12.5%

Black level: 72%

Blanking level: Sync pulses added - 75%

level

Pedestal: difference between black level and blanking level – tend to merge

Pedestal height: distance between the pedestal level and the dc level – indicates the average brightness

Picture information: 10% - 75%

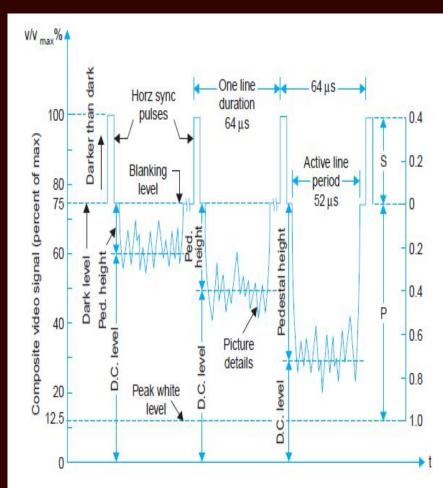


Fig. 3.1 Arbitrary picture signal details of three scanning lines with different average brightness levels. Note that picture to sync ratio P/S = 10/4.

Darker the picture – higher will be the voltage within those limits

DC component of the video signal

- Average value or dc component corresponding to the average brightness of the scene
- Average brightness can change only from frame to frame and not from line to line
- Low pedestal height scene darker
- Larger pedestal height higher average brightness

blanking pulses . . .

Make the retrace lines invisible by raising the signal amplitude slightly above the black level (75%)

Repetition rate of horizontal blanking pulse = scanning freq. = 15625Hz

Freq of vertical blanking pulse = field scanning freq. = 50 Hz

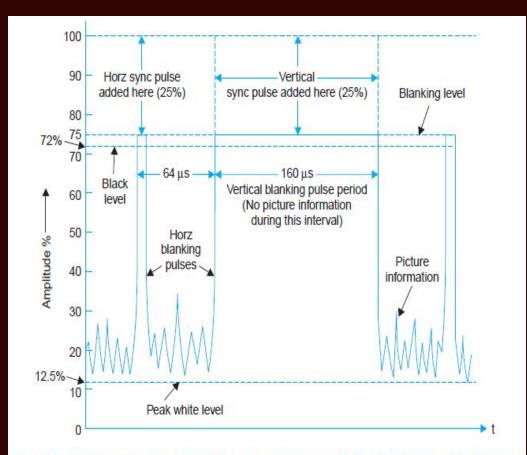


Fig. 3.2 Horizontal and vertical blanking pulses in video signal. Sync pulses are added above the blanking level and occupy upper 25% of the composite video signal amplitude.

Sync Pulse and Video Signal Amplitude Ratio P/S RATIO = 10/4

Justification:

- If the picture signal amplitude is ↑ at the expense of sync pulses – when S/N ratio at the receiver falls, sync pulse amplitude becomes insufficient to keep the picture locked
- If the sync pulse amplitude is ↑ at the expense of the picture signal, then the raster remains locked but the amplitude of the picture content will be too low
- P/S ratio of 10/4 represents the most efficient use of TV system

horizontal Sync details . . .

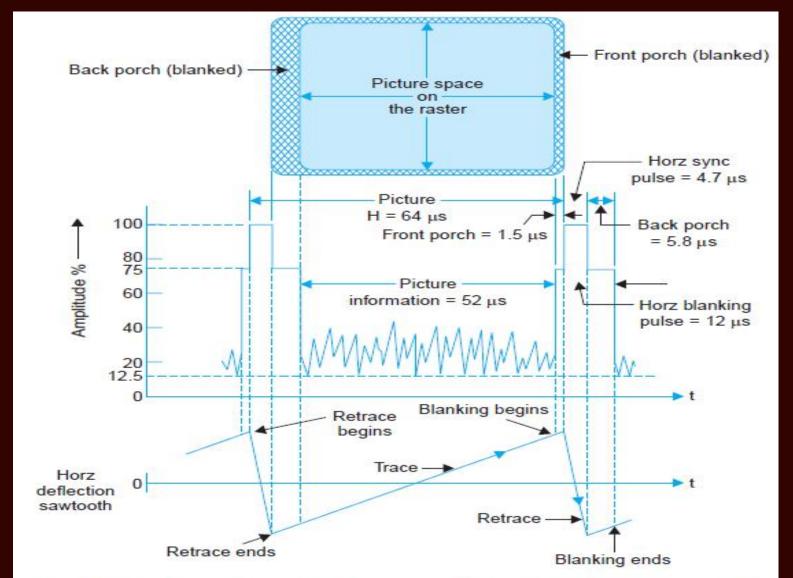


Fig. 3.3 Horz line and sync details compared to horizontal deflection sawtooth and picture space on the raster.

horizontal sync details

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- Total line period = 64μS
- Line blanking period = 12μS
- Differential leading edges are used for synchronizing horizontal scanning oscillator
- Divided into three sections :

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front porch: 1.5µS - allows the receiver video to settle down
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/// : 4.7 μS - for blanking the flyback/retrace
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- blacker than the black

back porch: 5.8µS - time for the horizontal time base circuit to reverse the direction of current for scanning the next line

- same amplitude as that of blanking level; used by AGC circuits at the receiver to develop true AGC voltage

Vertical Sync details

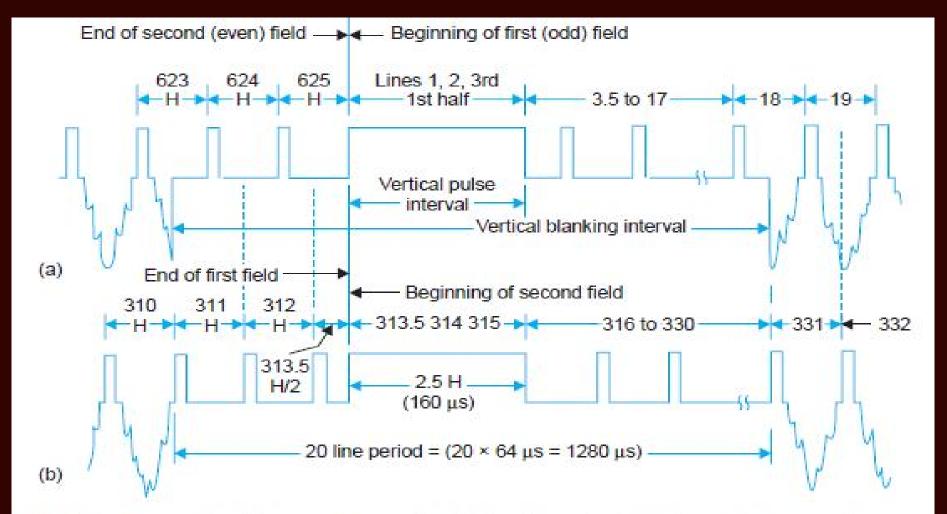


Fig. 3.4 Composite video waveforms showing horizontal and basic vertical sync pulses at the end of (a) second (even) field, (b) first (odd) field. Note, the widths of horizontal blanking intervals and sync pulses are exaggerated.

Vertical Sync details

...contd.

- Added after each fields
- Complex in nature
- Vertical sync period = 2.5 to 3 times the horizontal line period
- In 625 line system: $2.5 \times 64 = 160 \mu S$
- Commence at the end of first half of 313th line (end of first field) and terminates at the end of 315th line
- Similarly after an exact interval of 20mS (one field period), the next sync pulse occupies the line numbers 1st, 2nd and first half of 3rd.

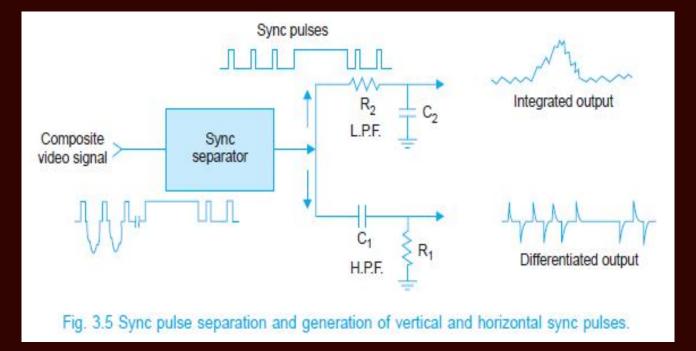
Vertical sync details

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 Horizontal sync information is extracted from the sync pulse train by differentiation i.e. Passing the pulse train through an HPF – leading edges are used to synchronize the horizontal scanning oscillator

 Furthermore, receivers often use monostable multivibrators to generate horizontal scan, and so a pulse is required to initiate each and every cycle of the horizontal oscillator in

the receiver.



Shortcomings and its solution

- 1. Horizontal sync pulses are available both during the active and blanked line periods but there are no sync pulses (leading edges) available during the 2.5 line vertical sync period horizontal sweep oscillator would tend to step out of synchronism during each vertical sync period
- The situation after an odd field is even worse
 - -since it begins at midway
 - -leading edge of the vertical sync pulse comes at wrong time to provide synchronism for the horizontal oscillator
- Therefore five narrow slots (4.7μS width) are cut in the vertical sync pulse at intervals of 32μS – rising edges are used to trigger horizontal oscillator.
- This insertion of short pulses : called notching of serration of the broad field pulses

Shortcomings and its solution



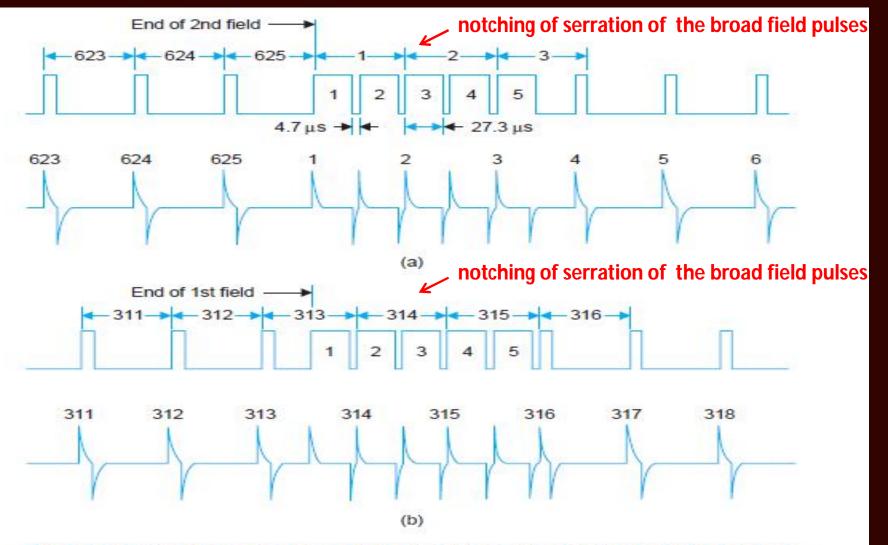


Fig. 3.6 Differentiating waveforms (a) pulses at the end of even (2nd) field and the corresponding output of the differentiator (H.P.F.) (b) pulses at the end of odd (1st) field and the corresponding output of the differentiator (H.P.F.) Note, the differentiated pulses bearing line numbers are the only ones needed at the end of each field.

Shortcomings and its solution

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- 2. It is seen that the synchronization of the vertical sweep oscillator in the receiver is obtained from vertical sync pulses by integrator (LPF)
- Voltage built across the capacitor of the LPF corresponding to the sync pulse trains of both the fields is shown in fig.

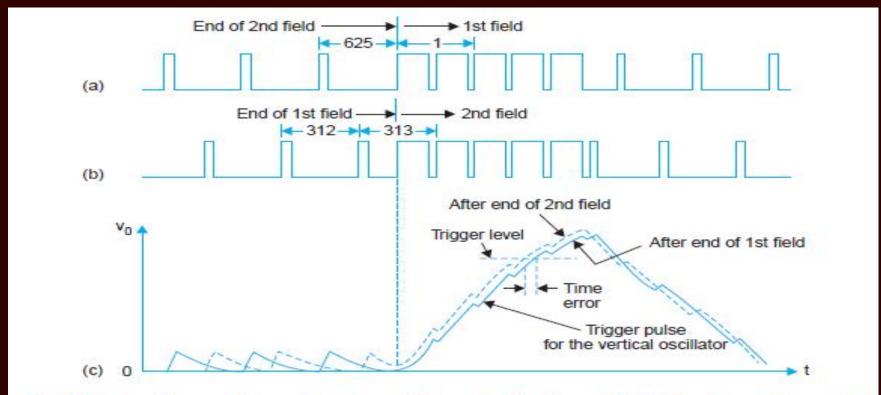


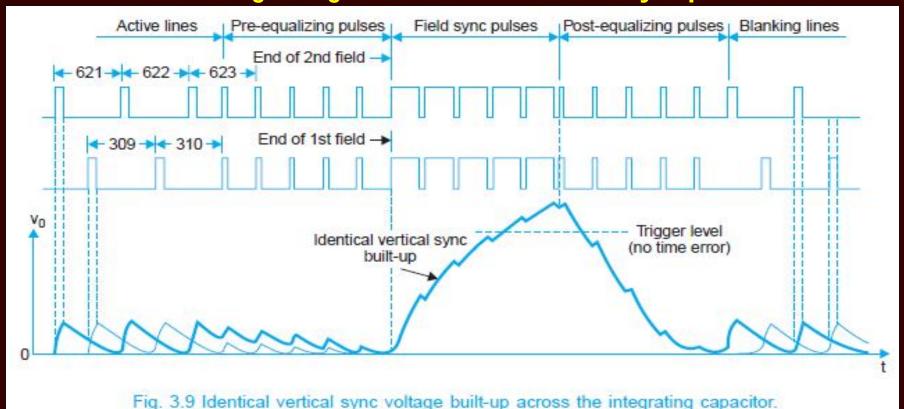
Fig. 3.7 Integrating waveforms (a) pulses at the end of 2nd (even) field (b) pulses at the end of 1st (odd) field (c) integrator output. Note the above sync pulses have purposely been drawn without equalizing pulses.

Shortcomings and its solutioncontd

- Each horizontal pulse cause a slight rise in voltage across the capacitor, but this is reduced to zero by the time the next pulse arrives (charging period=4.7μS and discharging period = 59.3μS)
- But during broad serrated region, capacitor has more time to charge and only 4.7µS to discharge
- Situation is different for the beginning of the 2nd field-here the last horizontal pulse corresponding to the beginning of the 313th line is separated from the first vertical pulse by only half-a-line.
- Therefore the voltage developed a/c the vertical filter will not have enough time to reach zero before the arrival of the 1st vertical pulse
- Hence the voltage developed a/c the o/p filter is some what higher at each instant as compared to the voltage developed at the beginning of the 1st field (shown as dotted chain)
- i.e. Oscillator get triggered a fraction of a second early as compared to the first field upset the desired interlacing sequence
- Equalizing pulses are used to solve this problem

Equalizing pulses

- Solves the shortcomings occurring on account of half line discrepancy
- Five narrow pulses of 2.5 line period are added on either side of the vertical sync pulses: known as pre-equalizing and post-equalizing pulses
- The effect of these pulses is to shift the half line discrepancy away from both the beginning and end of the vertical sync pulses



Equalizing pulses

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- Pre-equalizing pulses:
 - 2.3µS duration
 - result in the discharge of the capacitor to zero voltage in both the fields
- Post-equalizing pulses: necessary for a fast discharge of the capacitor to ensure triggering of the vertical oscillator at proper time
- With the insertion of equalizing pulses:
 - the voltage rise and fall profile is the same for both the field sequences
 - the vertical oscillator is triggered at the proper instants. i.e. exactly at an interval of 1/50th of a second.